REPORT

PRAGATI ENGINEERING COLLEGE

(Approved by AICTE, Permanently Affiliated to JNTUK, KAKINADA & Accredited by NBA)

1-378, A.D.B.Road, Surampalem, Near Peddapuram-533437



"HARVEST AUTOMATION"

Date: 22-8-2025

Day: Friday

Turing Club organised by the Dept. of CSE – AI&ML of Pragati Engineering College in association with Career Guidance Cell is organizing a seminar on "HARVEST AUTOMATION" as part of Industry 4.0.

Attendance list:



PRAGATI ENGINEERING COLLEGE

(AUTONOMOUS)

DEPARTMENT OF CSE (Artificial Intelligence & Machine Learning)

TURING CLUB

EVENT NAME: Harvest Automation

DATE: 22-8-2025

SPEAKER NAMES: M. Harshitha, K. Roshini, S. Swarcopa rani

The list of students attended for this event.

S.No	Rell No.	Name of the Student	Year	Signature
1.	2493194200	3+CV-Vishesh Von ma	2 nd	My
2.	24A31A42C6	S. Simon	2101	Sinon.
3	24×31×42C7	svs. Bhaskar	240	BUNNEY -
4.	24 A31A+285	I. Harabean	'S 10g	Itaaheath
5	24A31A42C2	R. Sandeep	2nd	R. Zander
6	25A35A4210	Ch. vave K	2 nd	ch. Wivek.
7.	24A31A42C0	To Charan Sanjay	2nd	T. Choicnelingay
9.	สินควเคย2 คๆ	D. Srisam Varma	and	D. Sham
q.	24A31A42B1	D. Mukesh Kumar	and	J. Mulcest kumar
10.	2HA31A4256	K. chaltanya kumar	2nd	K.chairany a kumarc
ţţ.	duaziaua D1	Str. Growtham varma	and	Gowtham
12.	25A35A4212	k-Vamsi tega	బ్ ^ర	K. Vani Cese
13	24A31A-42A4	A Rehit vijay	'2 ^{md}	A. Rohit Vijay
14.	24A31A42A5	B. Pavan Southesh	2 ⁿ²	B. Pavan Sounthork
15.	2U13/AU268	Sk. Alisha	end	en Alisha

Harrhitha Student coordinator

Faculty Coordinator



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S.No	Roll No.	Name of the Student	'Year	Signature	
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4.	2UA3IAU2Ho	G. Shankor Sujith II		G. Sharkarinth.	
5.	2UA31A42J1	S. Bharadusez	ш	Phonedisas	
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7	24A31A42J4	S.V.S. Hood hand	I	Systenborar	
8.	24A31A4239	k Jyothik pavan	I	к Гуоник рача	
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14	24A3IA 4253	P.H.C. Teja	T	g. H. chavonter	
15.	24 A 31 A 42 34	D. Hari Kichore	U	D. Hari Kishore	

Marylutta Student coordinator





(AUTONOMOUS)

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S.No	Roll No.	Name of the Student	Year	Signature
1.	24A31A4223	N.Gopike Nischala	<u>II</u>	N. Gopika
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4	24 A31A4209	G. Hima Bindu	fi	G. Bindy
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7.	24A31A4284	K. Sai Satya Depika	71	lux
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S.No	Roll No.	Name of the Student Y		Signature
1.	24A31A42D4	Ch. Padra Soil	T	Pasugly.
2.	24A31A42 E9	M. Harshikha	T	M. Hastilha
3.	24A81A42C20	T. Rabbola Sargu	T	T. Prabhata Saryu
ų.	24A3 1A42 F6	R· Niharika	I	R. Nihasika
5	24A31A42D6	D.H.V. D.V. Sryjano	·II	D. Brujano
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7.	24A31A42F8	S. Prasanna	I	S. Prayanna
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۹.	25A35#4214	K. Vyshnavi	I	K-4yb-
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15.	24A31A4216	k-svi nihadika	$\overline{\Pi}$	K.S.N?ham?ka.

Sarshithe Student coordinator

FEED BACK ANALYSIS

ID	NAME	ROLL NUMBER	YEAR	ABOUT THE SPEAKER	Technical content explanation	Any Suggestions
1	Sai Dhanushree chitturi	24A31A4207	2	4	3	
	Padilam. Deepika Satya					
2	Jaya Durga	24A31A4225	2nd year	5	5(EXCELLENT)	No suggestions
3	J.Siri chandana	24A31A4210	2 nd year	4	4	None
4	Dammala Hari Kishore	24A31A4234	2nd	4	4	
5	P SRAVYA	24A31A42F3	AIML	5	5(EXCELLENT)	No
6	Mary Blessica	24A31A4206	2nd	5	5(EXCELLENT)	No suggestions
7	Vanumu Yashodalakshmi	24A31A4230	2	4	5(EXCELLENT)	No
8	Narisetty Gopika Nischala	24A31A4223	2	4	5(EXCELLENT)	None
9	Piradi. Sai RupaSri	24A31A4227	2	4	4	No
10	Pasala charishma	24A31A4226	2	5	5(EXCELLENT)	
11	K.PUJITHA	24A31A4217	2ND YEAR	5	5(EXCELLENT)	
	Datla Sri Venkata Lakshmi					
12	Sowjanya	24A31A4208	2	5	5(EXCELLENT)	No suggestions
13	B.Sai Saranya	24A31A4205	2	5	5(EXCELLENT)	
14	K.Sri Niharika	24A31A4216	2nd	5	5(EXCELLENT)	
15	K Sowjanya Durga Lakshmi	24A31A4212	2	5	5(EXCELLENT)	
16	K.kanaka maha Lakshmi	24A31A42E3	2nd	4	3	No PROVIDE PRACTICLE
17	SK.mahaboob basha	24a31a42j3	2	4	5(EXCELLENT)	Intrested to do simple projects using this content
18	Duggana Dhanvy	24A31A42G9	2	4	5(EXCELLENT)	Good
19	Manohar vinnakoti	24a31a4265	2	4	5(EXCELLENT)	Communication
20				1	5(EXCELLENT)	
21	M.SIVARAMAKRISHNA	24A31A42I3	2nd p	1	5(EXCELLENT)	
22	Kopparthy Gayatri Devi	24A31A42E2	2nd	5	5(EXCELLENT)	
23	G.Tualsi Hima Bindu	24A31A4209	2	5	4	Impressive
24	VARUN DODDIPATLA	24A31A4235	2025	4	5(EXCELLENT)	GOOD

Overall rating: Good



Explore how cutting-edge robotics is revolutionising farming practices, enhancing efficiency, and promoting environmental sustainability.

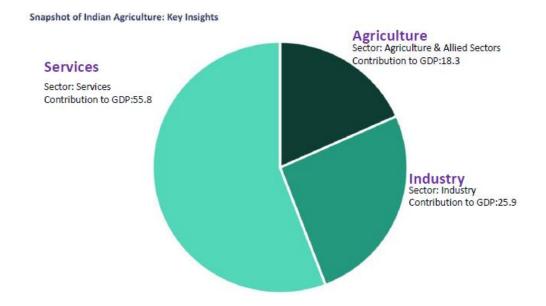
What is Harvesting Automation?

Advanced robotics for crop collection.

Harvesting automation utilizes **robots and intelligent systems** to perform tasks traditionally done by human labor.

This includes picking, sorting, and packing crops with enhanced speed and precision.





Revolutionizing Indian Agriculture: A Robotic Renaissance

This presentation explores the current landscape of Indian agriculture, highlighting critical challenges and presenting innovative solutions through the integration of robotics and advanced technologies. We aim to demonstrate how these advancements can enhance productivity, minimize food waste, and ensure sustainable growth for the sector.



Robotics: The Future of Farming



AGRICULTURAL ROBOTS

- Offer a transformative solution to many of the challenges faced by traditional farming
- Operate continuously, 24/7, without fatigue or the need for breaks, significantly increasing efficiency and reducing operational timelines

For instance, in tasks like seeding, weeding, spraying, and harvesting, robots can execute with unparalleled accuracy, minimizing waste of seeds, water, and fertilizers, and ensuring uniform treatment across fields. This precision not only boosts productivity but also contributes to more sustainable farming practices, reducing environmental impact.









Types of Agricultural Robots

Diverse applications for diverse needs.



Drones

Crop monitoring, spraying, data collection.



Autonomous Tractors

Plowing, planting, and cultivating without a driver.



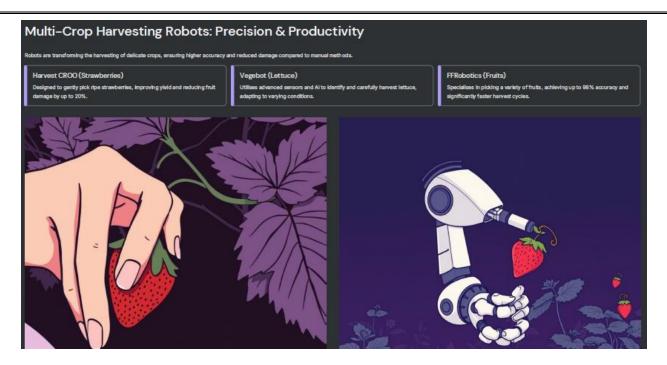
Harvesting Robots

Automated picking of fruits and vegetables.



Weeding Robots

Precision weeding, reducing herbicide use.



Case Study: Cashew Nut Plucking Robots

- · Cashew harvesting is notoriously labour-intensive and requires delicate handling to avoid damaging the nuts.
- Traditional methods expose workers to harsh conditions and potential hazards.
- Robotics offers a groundbreaking solution to these challenges.
- New autonomous cashew plucking robots utilize advanced Al-powered vision systems to identify ripe cashew nuts on trees precisely.
- These robots, whether ground-based or dronemounted, gently pluck the nuts, significantly reducing the need for human exposure to harsh weather and potential irritants from the cashew sap.
- This precision not only protects workers but also dramatically increases overall yield and reduces crop waste.





The Foundation of Our World: Agriculture

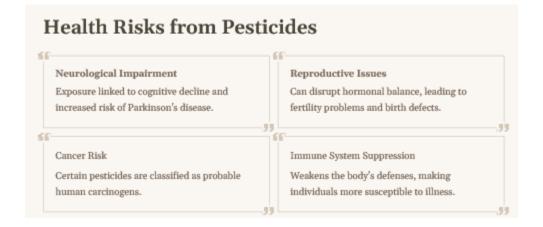
Agriculture is the backbone of civilization, providing sustenance and livelihood across the globe. Farmers, with their unwavering dedication, feed billions, making their work the bedrock of our society.

Manual Harvesting: The Hidden Costs

- Labor-intensive & Costly: High wages and significant manual effort drive up production costs.
- Physically
 Demanding: Repetitive
 tasks lead to fatigue and
 injuries for farmworkers.
- Inconsistent
 Ripeness: Subjective
 judgment causes
 variations in harvest
 quality.
- Quality Control
 Issues: Difficulty in maintaining uniform standards for freshness and appearance.



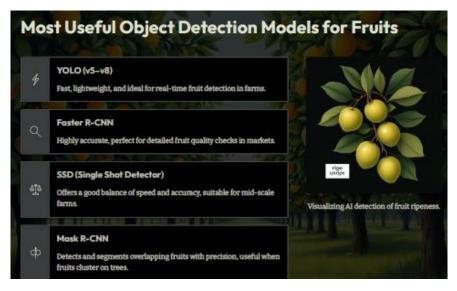
Understanding Agricultural Pesticides Pesticides are chemicals used to control pests that can harm crops. Their widespread adoption has significantly impacted agricultural practices. Farmers Using Pesticides Farmers Avoiding Pesticides A large majority of farmers currently rely on A smaller segment of agriculture opts for organic or pesticides to protect their yields. alternative pest control methods. Insecticides Target insects that damage crops. Herbicides Control unwanted weeds that compete with crops. Fungicides Prevent and control fungal diseases. Rodenticides Eliminate rodents like rats and mice. Bactericides



Why Al is Better than humans for Fruit Harvesting

Artificial Intelligence provides a natural and chemical-free way of identifying fruit ripeness, ensuring safe and healthy produce for consumers. Unlike human judgment, which can be inconsistent, AI offers accurate and consistent results by analyzing color, size, and texture. It is much faster than manual checking and can easily scale across large farms, helping farmers save time, reduce wastage, and deliver high-quality fruits to the market.





YOLO – Real-Time Object Detection

YOLO, standing for You Only Look Once, is a revolutionary object detection system that processes entire images in a single forward pass. It's known for its exceptional speed, making it ideal for real-time applications like fruit detection in dynamic environments.



Input Image

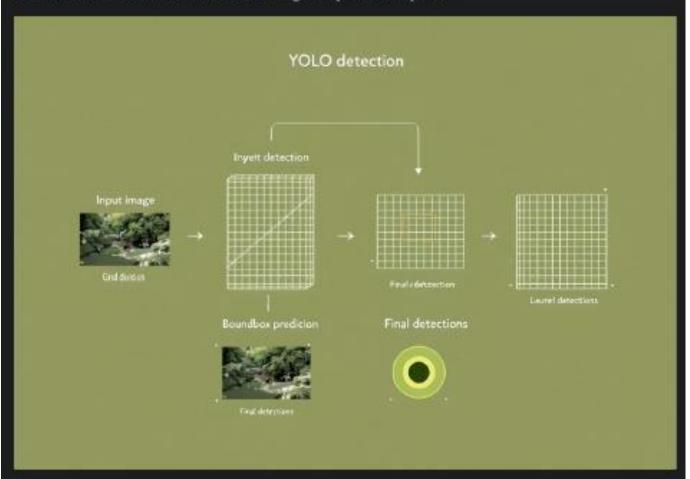
Grid Division

Boundin Boxes Class Probabilities Confidence Scores

This single-stage approach divides the image into a grid, with each cell simultaneously predicting bounding boxes, class probabilities, and confidence scores for detected objects, leading to incredibly fast and efficient performance.

YOLO — Single-stage, real-time object detection

You Only Look Once (YOLO) represents a paradigm shift in object detection. Unlike multi-stage approaches, YOLO detects all objects within an image in a single, streamlined pass through a convolutional neural network (CNN), leading to unparalleled speed.



How it works (Inference)

Grid Division

The input image is first divided into a fixed grid of cells.

Cell Predictions

Each grid cell is responsible for predicting bounding box coordinates (x, y, width, height), an objectness score (confidence of containing an object), and class probabilities for objects within that cell.

Non-Maximum Suppression (NMS)

Redundant or overlapping bounding boxes are then filtered out using NMS, resulting in a single, accurate detection for each object, such as ripe, unripe, or overripe fruits.

Affordable AI & Future Scope in Fruit Industry

Making Al Affordable for Farmers



Technology Costs Drop Over Time

Just like mobiles and internet, AI tools will become cheaper as adoption grows.

Subscription Models

Low-cost access to powerful AI models via cloud services.

Affordable Devices

Lightweight models like YOLOv5 can run on smartphones, not just supercomputers.

Future Scope of Al





Automated Harvesting

→ Robots or machines will pick ripe fruits automatically instead of laborers.

(Example: A robot arm plucking only ripe mangoes.)



Predictive Yields

→ Al will tell farmers in advance how much fruit they can expect in the next harvest.

(Example: Knowing "this season you'll get -500 kg of apples".)

Driving Growth in Agriculture: Al-Powered Fruit Detection

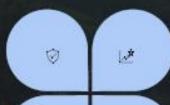
Our intelligent systems revolutionize fruit harvesting, bringing unprecedented efficiency, quality, and economic benefits to growers and consumers alike.

Health, Safety & Quality

- Chemical-free fruits
- Consistent grading
- Reduced food waste

Trust & Brand Value

- Proof of ripeness
- Transparent grading
- · Premium branding





Speed & Scale

- Hundreds scanned per minute
- 24/7 operation
- · Access difficult areas

Farmer & Market Economics

- Lower labor costs
- Reduced spoilage
- Better market prices

PHOTOS





Organises Seminar on

TAENG

HARVEST AUTOMATION

Speakers



S. Swaroopa rani 28A31A42J6



M. Harshitha



K. Roshini

22th August 2025

Timings : 111:00 AM - 12:00 PM

In Association with IAENG (International Association of engineers & Turing club)



Engineering College
(AUTONOMOUS)

















(AUTONOMOUS)

DEPARTMENT OF CSE (Artificial Intelligence & Machine Learning)

PEC / Admin / Circular / 2025 / Turing CLUB

Date: 20- 8-2025

All the staff, Pragati Turing club coordinators, Third year Students are informed that a seminar on "HARVEST AUTOMATION" is being organized by Turing club & IAENG in association with career Guidance cell. The details are given below.

Date: 22-08-2025

Time: I1:00 AM to 12:00 PM

Venue: F2

Faculty Co-Ordinator: Mrs. L. Yamuna

Student Co-Ordinator: M. HARSHITHA (III-year CSE (AI&ML)-23A31A4216)

Speaker: S. SWAROOPARANI (III -year CSE (AI&ML)-23A31A42J6)

K. ROSHINI (III-year CSE (AI&ML)-23A31A4208) M. HARSHITHA (III-year CSE (AI&ML)-23A31A4216)

Faculty coordinator

HoD-CSE (AI&ML)

Copy to:

- 1) Chairman / All Directors / Vice President for kind information.
- 2) Vice Principal/Dean T&P for information.
- 3) All HoDs are requested to circulate among your staff members.
- 4) Convener-Career Guidance cell
- 5) Office File.